# M12 Lexium MDrive®

## Simplifying machine building with compact integrated motors



**Programmable Motion Control version with circular connectors** Integrated stepper motors with on-board programmable motion controller for stand-alone operation and closed loop performance

CE 🖾 REACH IP65

**Kinetic-Systems** 

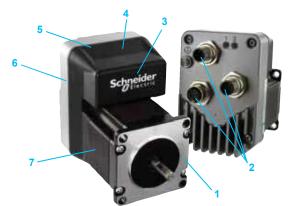
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## Description

## M12 Lexium MDrive® Motion Control

Fully programmable, RS-422/485 integrated 2-phase stepper motor with circular connectors

CE REACH



- rotary stepper motor
- 2 M12 sealed circular connectors
- 3 microstepping drive
- 4 programmable motion controller
- 5 up to 8 I/O lines
- 6 internal encoder option
- 7 closed loop performance

#### **Product offer**

M12 Lexium MDrive® Motion Control products integrate a high-torque 1.8° 2-phase stepper motor with on-board I/O and fully programmable motion controller, drive electronics, and closed loop performance with internal encoder option. This means programmable Motion Control products are stand-alone motion control solutions that can be used without an external controller.

M12 Lexium MDrive Motion Control products (LMD•M•C) have an RS-422/485 serial interface. Programming is with MCode, simple 1 to 2 character instructions, using the Lexium MDrive Software Suite provided free of charge. An optional Communication Converter Kit (part # MD-CC405-000) is recommended to facilitate prototyping.

Closed loop products (LMDCM•C) are equipped with 1000 line (4000 count/rev) encoders internal to the unit, requiring no extra space in an application. Encoders perform stall detection, position maintenance and find index mark, in addition to monitoring motor shaft position for real time closed loop feedback accomplished with hMTechnology.

Unlike traditional motor systems, hMT combines the best of servo and stepper motor technologies, while delivering unique capabilities and enhancements over both, including: – real time closed loop control – no loss of synchronization/stalling

- real time closed loop control
  full use of motor torgue
- torque mode control
- reduced motor heat (1)
- lower energy consumption (1)

#### Application areas

Lexium MDrive Motion Control products with circular connectors are ideal for machine builders who want an optimized motor with on-board electronics in a robust, sealed package. LMD closed loop products deliver enhanced performance, providing a lower cost option to servo motors in many applications. Integrated electronics of the fully programmable Lexium MDrive Motion Control products also reduce the potential for problems due to electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that will reduce system cost, design and assembly time for a large range of motion applications.

#### **Features**

- Integrated microstepping drive and high torque 1.8° 2-phase NEMA stepper motor
- Fully programmable integrated motion controller
- M12 sealed circular connectors
- Closed loop control with 1000 line internal encoder and hMTechnology (optional) – Prevents motor stalling while delivering numerous performance advantages
  - Variable current control reduces motor heat and lowers energy consumption
- Advanced current control for exceptional performance and smoothness
- RS-422/485 serial interface
  - +12 up to +70 VDC input power range
- Cost effective
- Extremely compact
- Up to 8 I/O
- Up to four +5 to +24 VDC signal inputs
- One 12 bit analog input
- Two 100mA power outputs (only LMD57 & LMD85 products)
- One 5.5mA high-speed signal output
- Auxiliary logic power supply input
- 20 microstep resolutions to 51,200 steps/rev including: Degrees, Metric, Arc Minutes
- Programmable motor run and hold currents
- 62 software addresses for multi-drop communications
- 336 user program labels / 11,120 bytes flash memory
- 0 to 2.56 MHz step clock rate selectable in 0.59 Hz increments
- Motor stack lengths: single, double and triple
- Graphical user interface provided for quick and easy configuration
- (1) Achieved with hMTechnology variable current control.

## Specifications

## M12 Lexium MDrive® Motion Control

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			LMD•M57•C (NEMA23)	LMD•M85•C (NEMA34)	
nput power	Voltage		+12+60 VDC	+12+70 VDC	
	Current maximum (1)		3.5 A	4.0A	
O sourcing or	Number of I/O	Analog input	1	1	
inking		Signal inputs	4	4	
		Power outputs	2	2	
		Signal outputs	1	1	
	Analog input	Resolution	12 bit		
	<b>U</b> .	Voltage range	0+5 VDC, 0+10 VDC, 020	mA, 420 mA	
	Signal inputs	Voltage range	+5 +24 VDC, TTL level compatib		
		Protection	over temp, short circuit, transient	, over voltage, inductive clamp	
	Power outputs	Current rating	-100+100mA	· · · · ·	
	·	Voltage range	-24+24 VDC		
	High-speed signal output	Current open collector/emitter	5.5 mA		
		Voltage open collector	+60 VDC		
		Voltage open emitter	+7 VDC		
Thermal	Operating temp	Heat sink maximum	85°C		
	non-condensing	Motor maximum	100°C		
Protection	Туре	Temp warning	084°C, user selectable		
		Earth grounding	via product chassis ground lug		
		IP rating	IP65	IP20	
Aux. logic input	Voltage range (2)		+12+24 VDC		
Communication	Туре		RS-422/485		
	Baud rate		4.8115.2 kbps		
Notion	Microstep resolution	Number of settings	20		
		Steps per revolution		, 3200, 5000, 6400, 10000, 12800, 20000, 200, 36000 (0.01 deg/µstep), 21600 (1 arc µstep)	
	Encoder (3)	Line count	1000 lines/4000 edges per rev		
		Style	internal, magnetic		
	Counters	Туре	position, encoder/32 bit		
		Edge rate maximum	5 MHz		
	Velocity	Range	+/- 2,560,000 steps per second		
	-	Resolution	0.5961 steps per second		
	Accel/Decel	Range	1.5 x 10 <sup>9</sup> steps per second <sup>2</sup>		
		Resolution	90.9 steps per second <sup>2</sup>		
Software	Program storage	Type/size	flash / 11,120		
	User registers		four 32 bit		
	User program labels & variat	oles	336		
	Math functions		+, -, ×, ÷, >, <, =, <=, >=, AND, C	R, XOR, NOT	
	Branch functions		Branch and Call		
	General purpose I/O functions	Inputs	home, limit plus, limit minus, go, si general purpose	top, pause, jog plus, jog minus, reset, capture	
		Outputs	moving, error, stall, velocity chan position, hMT active, make up ac	ge, general purpose, locked rotor, moving to title, attention	
	Trip functions		trip on input, trip on position, trip	on time, trip capture, trip on relative position	
	Party mode addresses		62		
	Encoder functions		stall detection, position maintena	nce find index	

(1) Actual power supply current will depend on voltage and load.
 (2) When input voltage is removed, maintains power only to control and feedback circuits.
 (3) Only with Lexium MDrive closed loop/encoder products.

An optional Communication Converter Kit is recommended to facilitate prototyping.

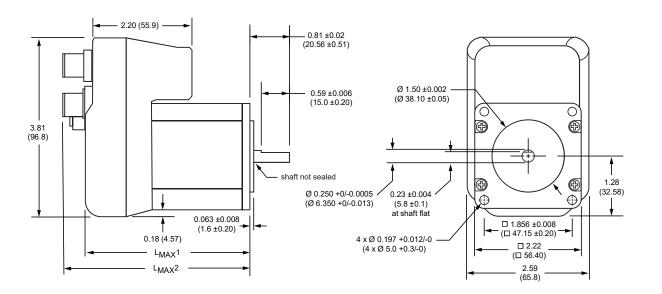


Dimensions

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#### LMD-57-C NEMA23 motor - dimensions in inches (mm)

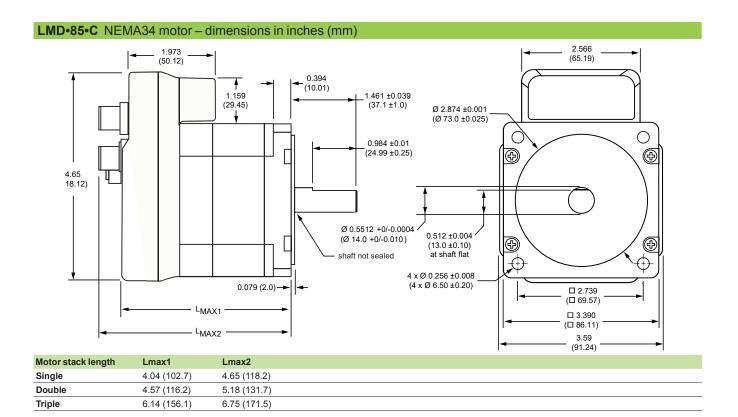


Motor stack length	Lmax1	Lmax2
Single	3.22 (81.8)	3.83 (97.3)
Double	3.56 (90.4)	4.21 (106.9)
Triple	4.44 (112.7)	5.06 (128.5)

## Dimensions

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## Connectivity and signal indicators

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#### Software interface

The free Lexium MDrive Software Suite includes a user interface GUI for product commissioning and programming via a PC.

PC interface is easily accomplished using the USB to RS-422/485 Communication Converter Kit (part # MD-CC405-000). Compatible with 32- and 64-bit Windows, Mac OS, and Linux operating systems. Each kit includes a communication converter and 5.0'/1.5m cordset with M12 mating connector.

#### Connectors

All Lexium MDrive connectors are conveniently grouped on the back of each product. Circular M12 connectors are used consistently on all motor sizes, with gender and keying features for correct connecting. Cordsets and a Communication Converter Kit are available to facilitate rapid prototyping.

A #6-32 screw lug is provided for earth grounding.

Connector	Style	Assignment
P1	M12 4-pin male	Supply voltage
P2	M12 12-pin male	I/O and multifunction interface
P3	M12 5-pin female	Communication
Chassis ground	#6-32 screw lug	Earth grounding

#### **Status indicators**

Lexium MDrive products include 2 LED signal indicators. The multi-color LEDs are programmed to indicate a range of pre-defined messages to aid users. See product user manual for details.



P2: I/O & multifunction M12 12-pin male

LEDs

## Part numbers

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Part numbers									
Example	L	Μ	D	С	М	5	7	1	С
Product LMD = Lexium MDrive	L	Μ	D	С	Μ	5	7	1	С
Control type C = Closed loop / with hMT and encoder (1) O = Open loop / no hMT or encoder	L	Μ	D	С	Μ	5	7	1	С
Communication type M = Motion Control via RS-422/485 serial interface	L	Μ	D	С	М	5	7	1	С
Flange size 57 = NEMA 23 / 57mm 85 = NEMA 34 / 85mm	L	Μ	D	С	M	5	7	1	С
Motor length 1 = single stack 2 = double stack 3 = triple stack	L	Μ	D	С	Μ	5	7	1	С
Variation C = M12 circular connectors	L	Μ	D	С	Μ	5	7	1	С

(1) Closed loop control delivers encoder feedback and hMT enhanced motor performance.

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Installation accessories			
Description	Length M	Length feet	Reference
Communication converter kit, USB to RS			
<ul> <li>For RS-422/485 products. USB-pluggable converter to set/program communication parameters in 32- or 64-bit. Kit includes communication converter and pre-wired shielded cable with M12 mating connector.</li> <li>Mates to M12 5-pin female communication connector</li> </ul>	1.5	5.0	MD-CC405-000
Communication cordset			
Shielded cable with straight M12 5-pin male connector.			
Mates to M12 5-pin female communication connector	3.0	10.0	MD-CS600-000
Power cordset			
Pre-wired shielded cable with straight M12 connector.			
Mates to M12 4-pin male power connector	3.0	10.0	MD-CS620-000

### I/O cordset Pre-wired shielded cable with straight M12 connector.

MD-CS610-000 Mates to M12 12-pin male I/O connector 3.0 10.0

## System performance

## Lexium MDrive® Motor specifications

LMD-57 NEMA 23 motor specifications						
	Motor stack length	Single	Double	Triple		
Holding torque	oz-in	103.4	158.6	242.2		
Holding torque	N-cm	73.0	112.0	171.0		
Detent formus	oz-in	3.9	5.6	9.72		
Detent torque	N-cm	2.7	3.9	6.86		
Rotor inertia	oz-in-sec2	0.0025	0.0037	0.0065		
Rotor mertia	kg-cm <sup>2</sup>	0.18	0.26	0.46		
Dedial load limit contar of choft	lbs	15	15	15		
Radial load limit, center of shaft	kg	6.8	6.8	6.8		
Axial load limit	lbs	20	20	20		
@ 1500 rpm (5000 full steps / sec)	kg	9	9	9		
Mainht (mater I driver)	OZ	26.4	31.2	44.0		
Weight (motor+driver)	g	748	885	1247		

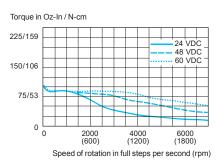
#### LMD-85 NEMA34 motor specifications

	Motor stack length	Single	Double	Triple
Holding torque	oz-in	336.0	480.0	920.0
Holding torque	N-cm	237.0	339.0	650.0
Detent torque	oz-in	10.9	14.16	19.83
Detent torque	N-cm	7.7	10.0	14.0
Rotor inertia	oz-in-sec <sup>2</sup>	0.0127	0.0191	0.0382
	kg-cm <sup>2</sup>	0.90	1.35	2.70
Pedial load limit contar of chaft	lbs	65	65	65
Radial load limit, center of shaft	kg	29.4	29.4	29.4
Axial load limit	lbs	20	20	20
@ 1500 rpm (5000 full steps / sec)	kg	9	9	9
	lb	4.45	5.65	9.0
Weight (motor+driver)	kg	2.02	2.56	4.08

## System performance

## Lexium MDrive<sup>®</sup> Speed torque characteristics

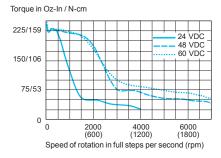
#### LMD•57 NEMA 23 speed torque (1) Single stack length



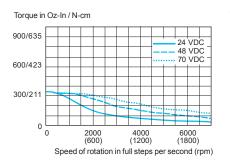
#### Torque in Oz-In / N-cm 225/159 150/106 75/53 0 0 2000 (600) 4000 (1200) (1800)

#### Speed of rotation in full steps per second (rpm)

#### Triple stack length

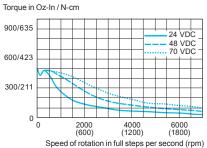


#### LMD•85 NEMA34 speed torque (2) Single stack length

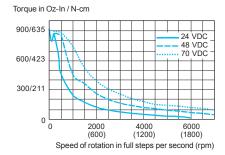


#### **Double stack length**

**Double stack length** 



### Triple stack length



(1) Test conditions: 100% current, 0.84 oz. damper, 0.18589 oz-in² inertia, hMT off (2) Test conditions: 100% current, 3.7 oz. damper, 4.75670 oz-in² inertia, hMT off